VLAB

Robotic Dexterity

Grabbing the Brass Ring

From warehouse operations to surgical operations, robots are lending a helping hand like never before. With a rapidly improving ability to manipulate objects of all shapes and sizes, they have the potential to replace human operators with better accuracy, better precision, and better efficiency.

In Robotic Dexterity, we will explore how the latest advances in robotic technologies have the potential to transform entire industries. By combining cloud computing and machine learning with groundbreaking gripper designs, these innovations in dexterity are shaping our future — sometimes literally.

Our panel of founders and industry insiders will explore these and other issues.

- Where are the best opportunities for entrepreneurs?
- Will these new robots completely replace all human workforces?
- How will society react to increasingly capable robots?

Join us on April 24 to find out what the future has in store.

Moderator

Stefano Carpin Professor of Electrical Engineering and Computer Science, UC Merced

Panelists

Harsha Prahlad, Co-Founder, CTO, & Products Officer, Grabit

Juan Aparicio Ojea, Head of Research Group, Advanced Manufacturing Automation, Siemens

Tuesday, April 24, 2018

6:00 pm – 8:30 pm

6:00 pm: Reception and demos 7:00 pm: Panel discussion (with Q&A)

Stanford Faculty Club Stanford University 439 Lagunita Drive Stanford, CA 94305

Register at the link below.

https://www.vlab.org/events/robotic-dexterity/